



# **Radar Systems Engineering**

## **Lecture 4**

### **The Radar Equation**

**Dr. Robert M. O'Donnell**  
**IEEE New Hampshire Section**  
**Guest Lecturer**

---

IEEE New Hampshire Section



# Block Diagram of Radar System

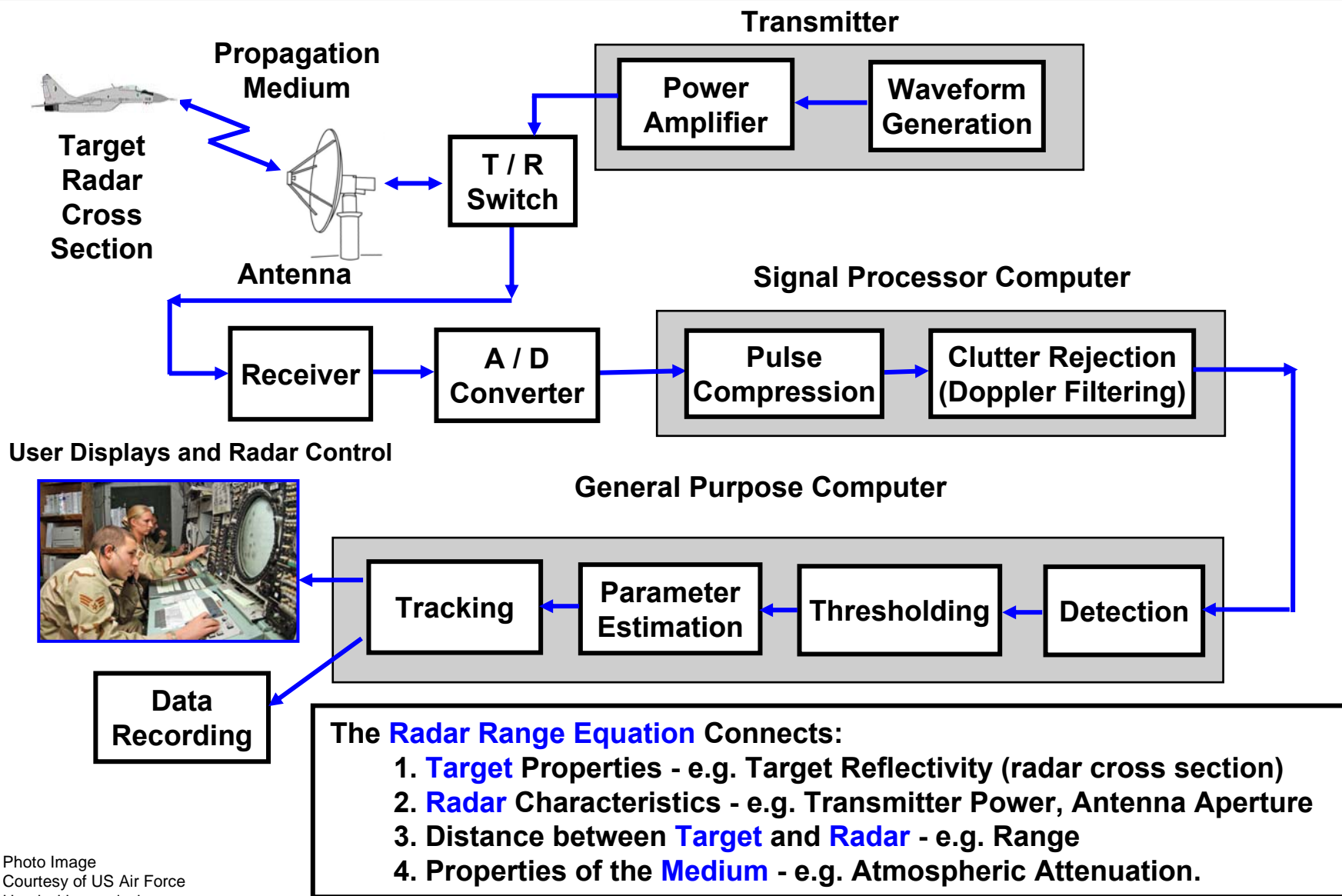


Photo Image  
Courtesy of US Air Force  
Used with permission.



# Outline



- Introduction
- ➔ • Introduction to Radar Equation
- Surveillance Form of Radar Equation
- Radar Equation for Rain Clutter
- Radar Losses
- Examples
- Summary



# Key Radar Functions



- **Detection**
  - **Illuminate selected area with enough energy to detect targets of interest**
- **Measure target observables**
  - **Measure range, Doppler and angular position of detected targets**
- **Track**
  - **Correlate successive target detections as coming from same object and refine state vector of target**
- **Identification**
  - **Determine what target is - Is it a threat ?**
- **Handover**
  - **Pass the target on to;**
    - Missile interceptor**
    - Data Collection function**
    - Air Traffic Controller / Operator**



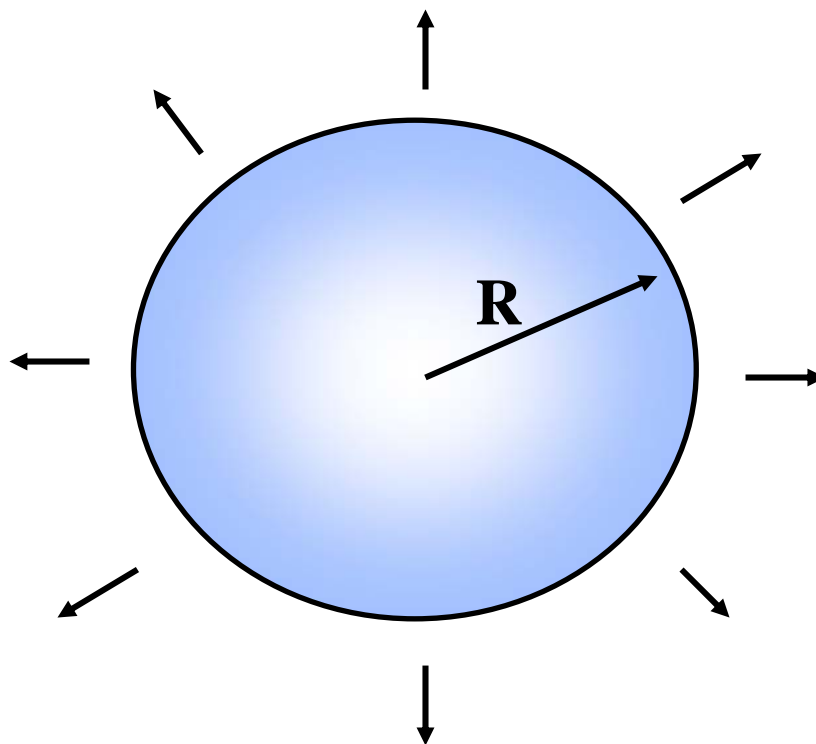
# Radar Range Equation



Power density from  
uniformly radiating antenna  
transmitting spherical wave

$$\frac{P_t}{4\pi R^2}$$

$P_t$  = peak transmitter  
power  
 $R$  = distance from radar



Courtesy of MIT Lincoln Laboratory  
Used with Permission



# Radar Range Equation (continued)



Power density from isotropic antenna

$$\frac{P_t}{4\pi R^2}$$

$P_t$  = peak transmitter power

$R$  = distance from radar

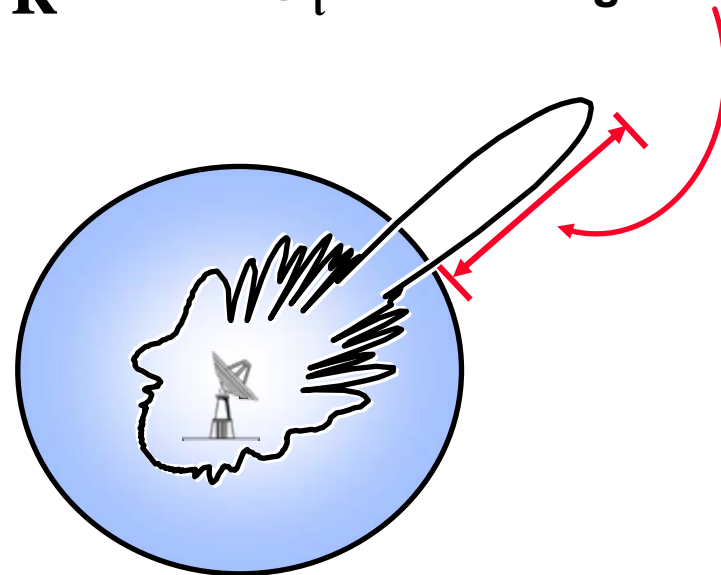
Power density from directive antenna

$$\frac{P_t G_t}{4\pi R^2}$$

$G_t$  = transmit gain

**Gain** is the radiation intensity of the antenna in a given direction over that of an isotropic (uniformly radiating) source

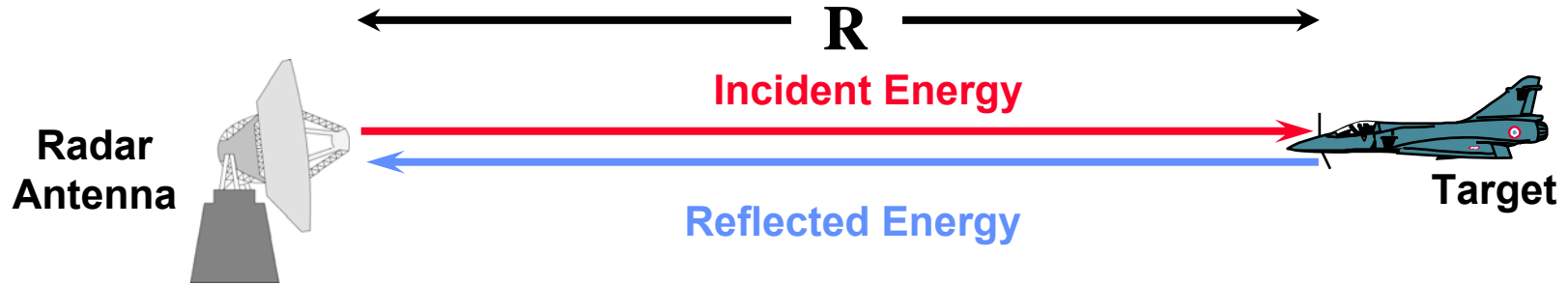
$$G_t = \frac{4\pi A}{\lambda^2}$$



Courtesy of MIT Lincoln Laboratory  
Used with Permission



# Definition of Radar Cross Section (RCS or $\sigma$ )



**Radar Cross Section (RCS or  $\sigma$ )** is a measure of the energy that a radar target intercepts and scatters back toward the radar

Power of reflected signal **at target**

$$\frac{P_t G_t \sigma}{4\pi R^2}$$

$\sigma$  = radar cross section units (meters)<sup>2</sup>

Power density of reflected signal **at the radar**

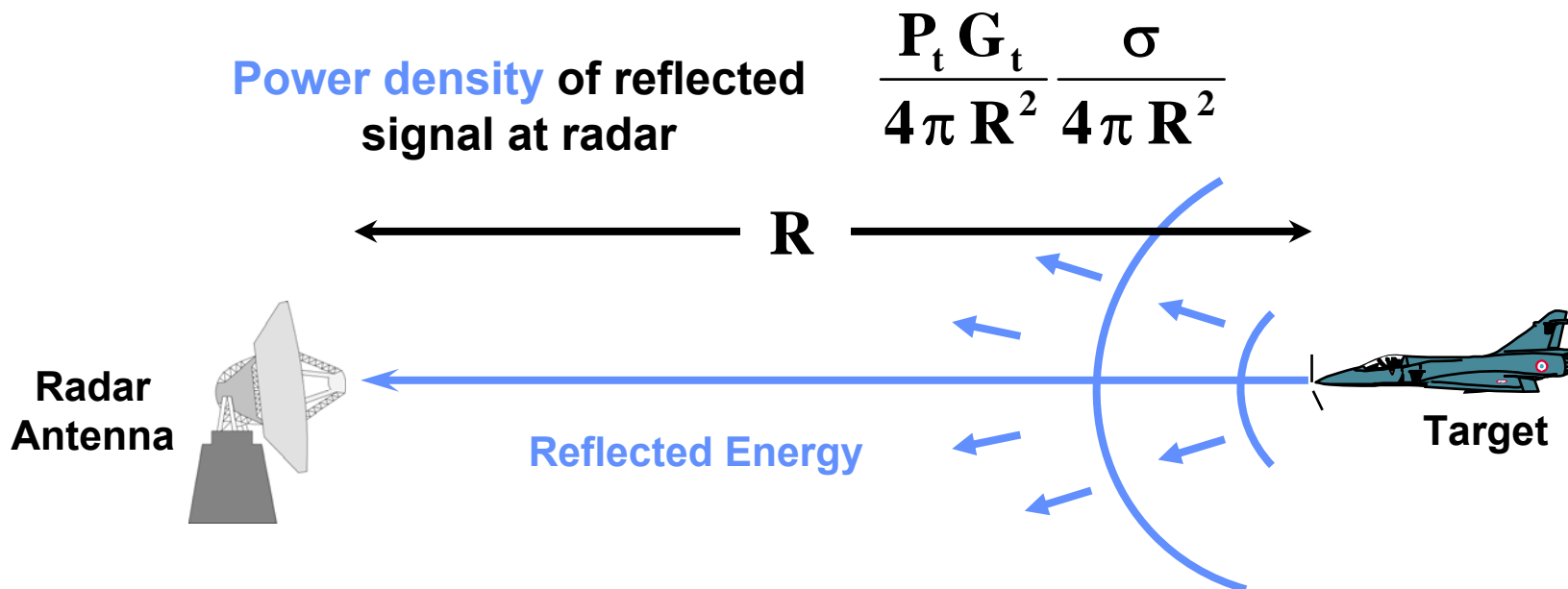
$$\frac{P_t G_t}{4\pi R^2} \frac{\sigma}{4\pi R^2}$$

Power density of reflected signal falls off as  $(1/R^2)$

Courtesy of MIT Lincoln Laboratory  
Used with Permission



# Radar Range Equation (continued)



The received power = the power density at the radar times the area of the receiving antenna

**Power** of reflected signal from target and received by radar

$$P_r = \frac{P_t G_t}{4\pi R^2} \frac{\sigma A_e}{4\pi R^2}$$

$P_r$  = power received

$A_e$  = effective area of receiving antenna

Courtesy of MIT Lincoln Laboratory  
Used with Permission



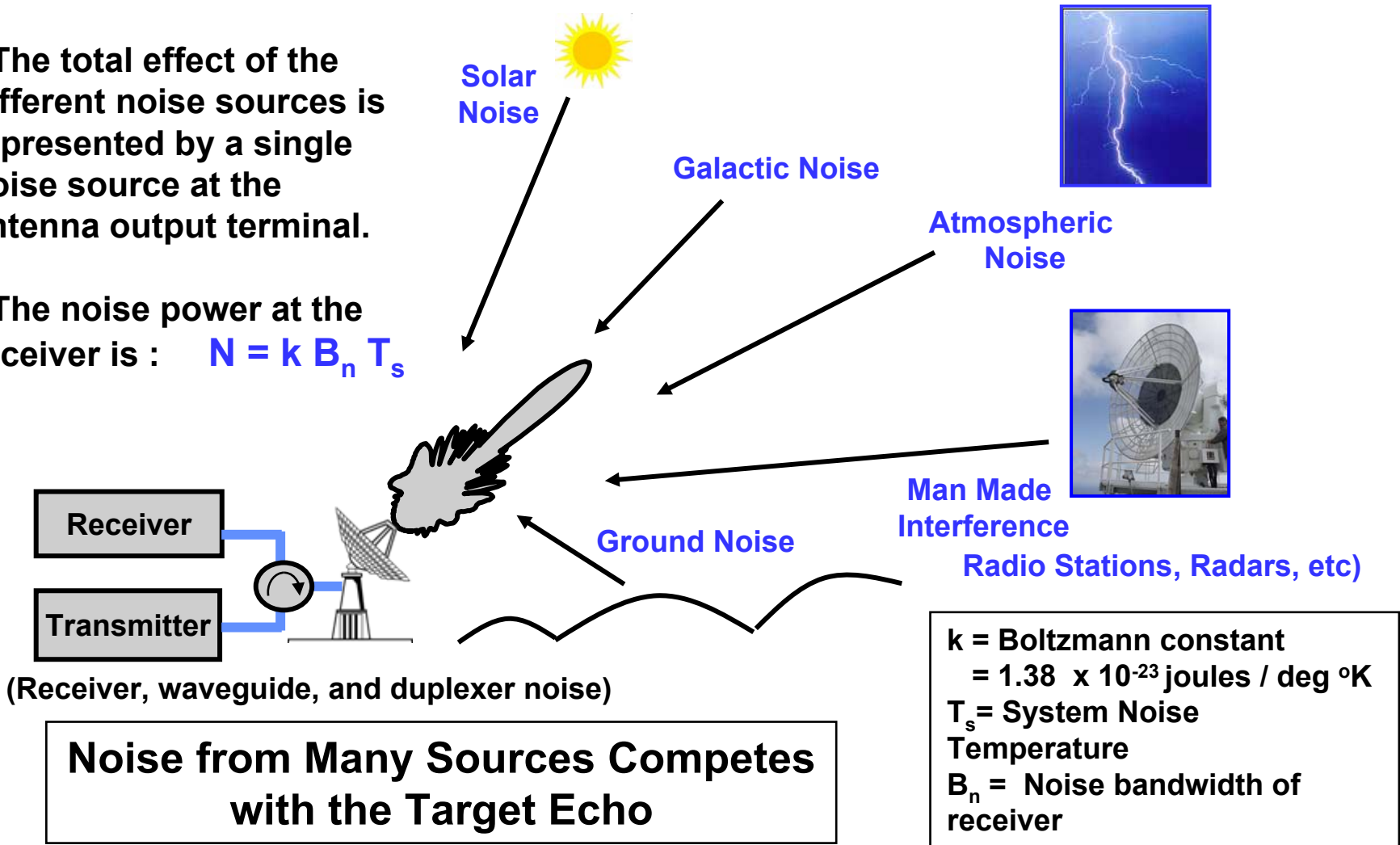


# Sources of Noise Received by Radar



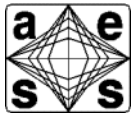
- The total effect of the different noise sources is represented by a single noise source at the antenna output terminal.

- The noise power at the receiver is :  $N = k B_n T_s$





# Radar Range Equation (continued)



**Signal Power** reflected  
from target and  
received by radar

$$P_r = \frac{P_t G_t}{4\pi R^2} \frac{\sigma A_e}{4\pi R^2}$$

**Average Noise Power**

$$N = k B_n T_s$$

**Signal to Noise Ratio**

$$\frac{S}{N} = \frac{P_r}{N}$$

**Assumptions :**

$$G = G_r = G_t$$

**L = Total System**

**Losses**

$$T_0 = 290^\circ \text{K}$$

$$\frac{S}{N} = \frac{P_t G^2 \lambda^2 \sigma}{(4\pi)^3 R^4 k T_s B_n L}$$

Courtesy of MIT Lincoln Laboratory  
Used with Permission

**Signal to Noise Ratio (S/N or SNR)** is the standard measure of a radar's ability to detect a given target at a given range from the radar

**“ S/N = 13 dB on a 1 m<sup>2</sup> target at a range of 1000 km”**

radar cross section  
of target





# System Noise Temperature



The System Noise Temperature,  $T_s$ , is divided into 3 components :

Where: 
$$T_s = T_a + T_r + L_r T_e$$
  
 $T_a$  is the contribution from the antenna  
 $T_r$  is the contribution from the RF components  
between the antenna and the receiver

$L_r$  is loss of the input RF components (natural units)  
 $T_e$  is temperature of the receiver

The 3 temperature components can be broken down further :

$$T_a = (0.88 T_{\text{sky}} - 254) / (L_a + 290)$$

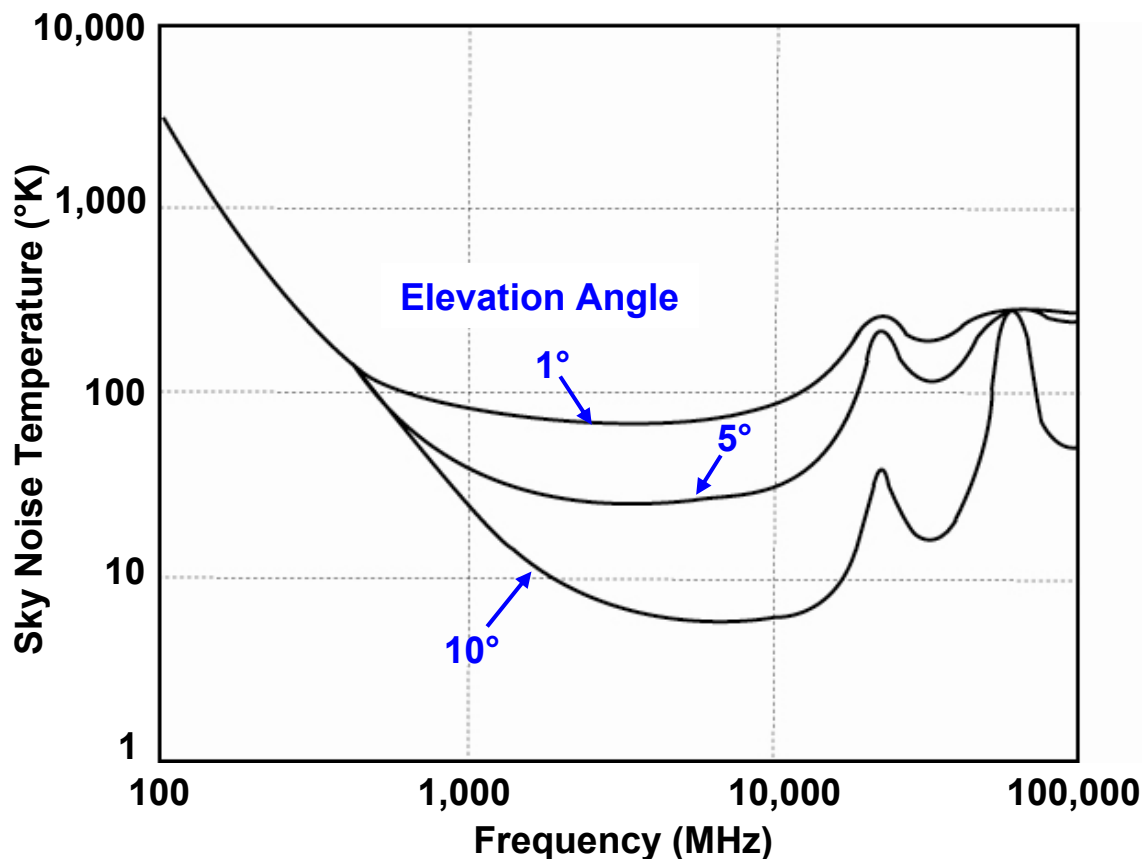
Where: 
$$T_r = T_{\text{tr}} (L_r - 1) \quad \text{and} \quad T_e = T_0 (F_n - 1)$$

$T_{\text{sky}}$  is the apparent temperature of the sky (from graph)  
 $L_a$  is the dissipative loss within the antenna (natural units)  
 $T_{\text{tr}}$  is physical temperature of the RF components  
 $F_n$  is the noise factor of the receiver (natural units)  
 $T_0$  is the reference temperature of 290° K

Note that all temperature quantities are in units of °K



# Noise Temperature vs. Frequency

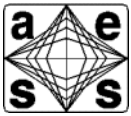


- The data on this graph takes into account the following effects:
  - Galactic noise, cosmic blackbody radiation, solar noise, and atmospheric noise due to the troposphere

(Adapted from Blake, Reference 5, p 170)



# Outline



- Introduction
- Introduction to Radar Equation
- ➔ • Surveillance Form of Radar Equation
- Radar Equation for Rain Clutter
- Radar Losses
- Examples
- Summary



# Track Radar Equation

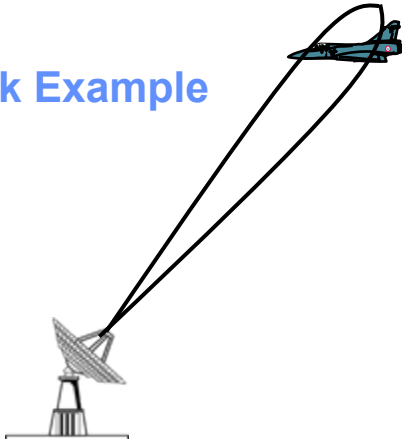


## Track Radar Equation

$$\frac{S}{N} = \frac{P_t G^2 \lambda^2 \sigma}{(4\pi)^3 R^4 k T_s B_n L}$$

- When the location of a target is known and the antenna is pointed toward the target.

## Track Example



Courtesy of MIT Lincoln Laboratory  
Used with Permission

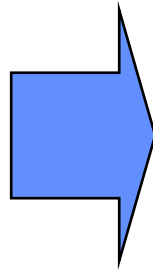


# Development of Search Radar Equation



## Track Radar Equation

$$\frac{S}{N} = \frac{P_t G^2 \lambda^2 \sigma}{(4\pi)^3 R^4 k T_s B_n L}$$

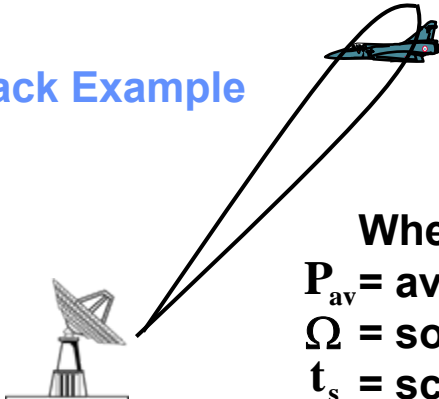


## Search Radar Equation

$$\frac{S}{N} = \frac{P_{av} A_e t_s \sigma}{4\pi \Omega R^4 k T_s L}$$

- When the location of a target is known and the antenna is pointed toward the target.

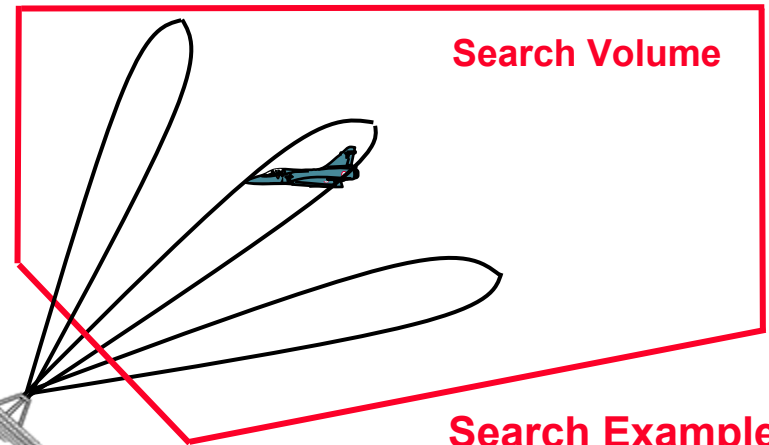
## Track Example



Where:

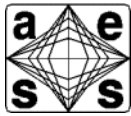
- $P_{av}$  = average power
- $\Omega$  = solid angle searched
- $t_s$  = scan time for  $\Omega$
- $A_e$  = antenna area

- When the target's location is unknown, and the radar has to search a large angular region to find it.



## Search Example

Courtesy of MIT Lincoln Laboratory  
Used with Permission



# Search Radar Range Equation

$$\frac{S}{N} = \frac{P_{av} A_e t_s \sigma}{4\pi \Omega R^4 k T_s L}$$

Re-write as:

f (design parameters) = g (**performance parameters**)

$$\frac{P_{av} A_e}{k T_s L} = \frac{4\pi \Omega R^4 \frac{S}{N}}{\sigma t_s}$$

Angular coverage  
 Range coverage  
 Measurement quality  
 Time required  
 Target size

Courtesy of MIT Lincoln Laboratory  
Used with Permission





# Scaling of Radar Equation



$$\frac{S}{N} = \frac{P_{av} A_e t_s \sigma}{4\pi \Omega R^4 k T_s L} \quad \longrightarrow \quad P_{av} = \frac{4\pi R^4 \Omega k T_s L (S/N)}{A_e t_s \sigma}$$

- **Power required is:**
  - Independent of wavelength
  - A very strong function of  $R$
  - A linear function of everything else

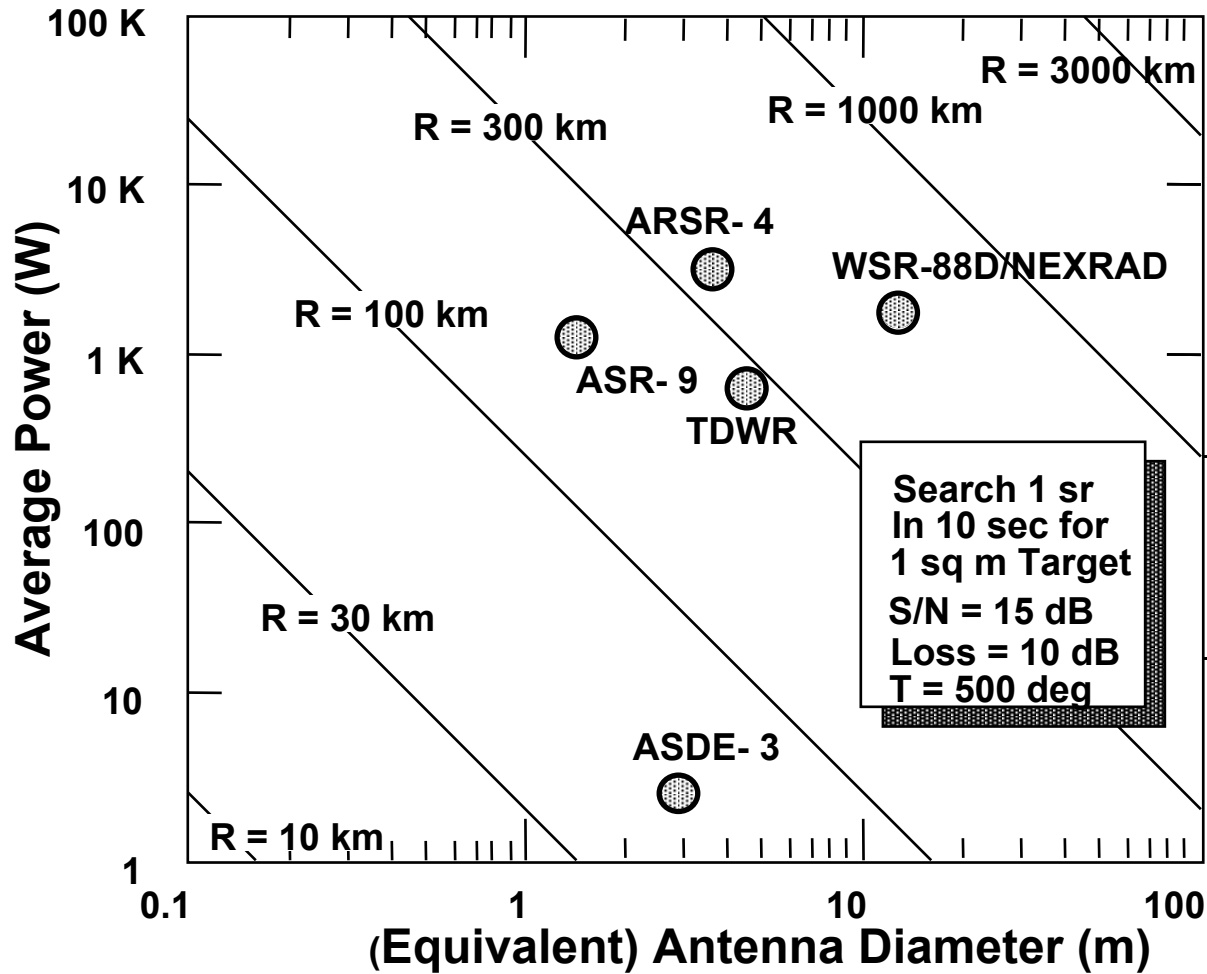
**Example**     Radar Can Perform Search at 1000 km Range  
How Might It Be Modified to Work at 2000 km ?

**Solutions** Increasing  $R$  by 3 dB (x 2) Can Be Achieved by:

1. Increasing  $P_{av}$  by 12 dB (x 16)
- or 2. Increasing Diameter by 6 dB ( $A_e$  by 12 dB)
- or 3. Increasing  $t_s$  by 12 dB
- or 4. Decreasing  $\Omega$  by 12 dB
- or 5. Increasing  $\sigma$  by 12 dB
- or 6. **An Appropriate Combination of the Above**



# Search Radar Performance



**ASR-9**  
Airport Surveillance Radar

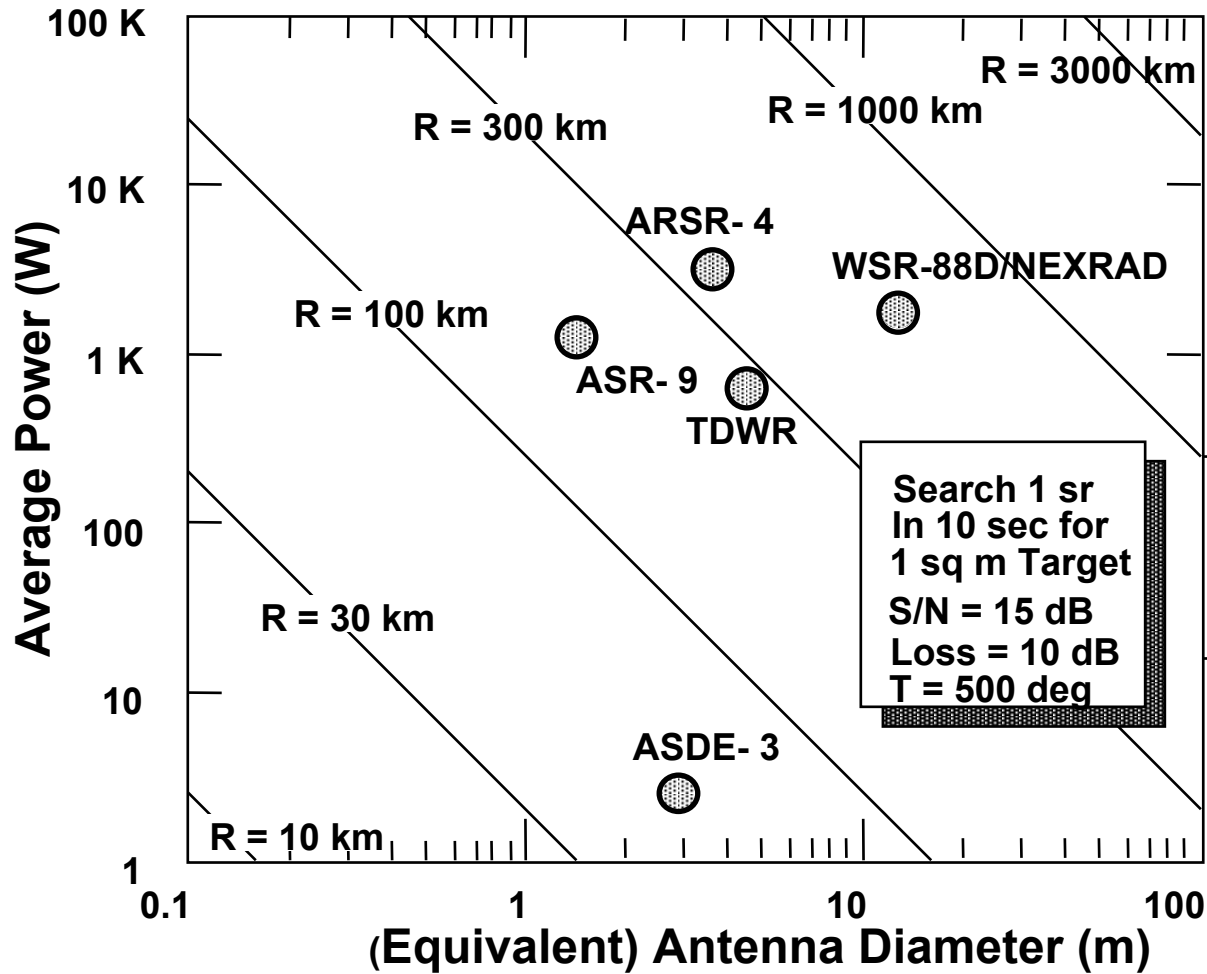
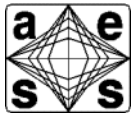


Courtesy of MIT Lincoln Laboratory.  
Used with permission.

Courtesy of MIT Lincoln Laboratory  
Used with Permission



# Search Radar Performance



**ASDE-3**  
Airport Surface Detection  
Equipment

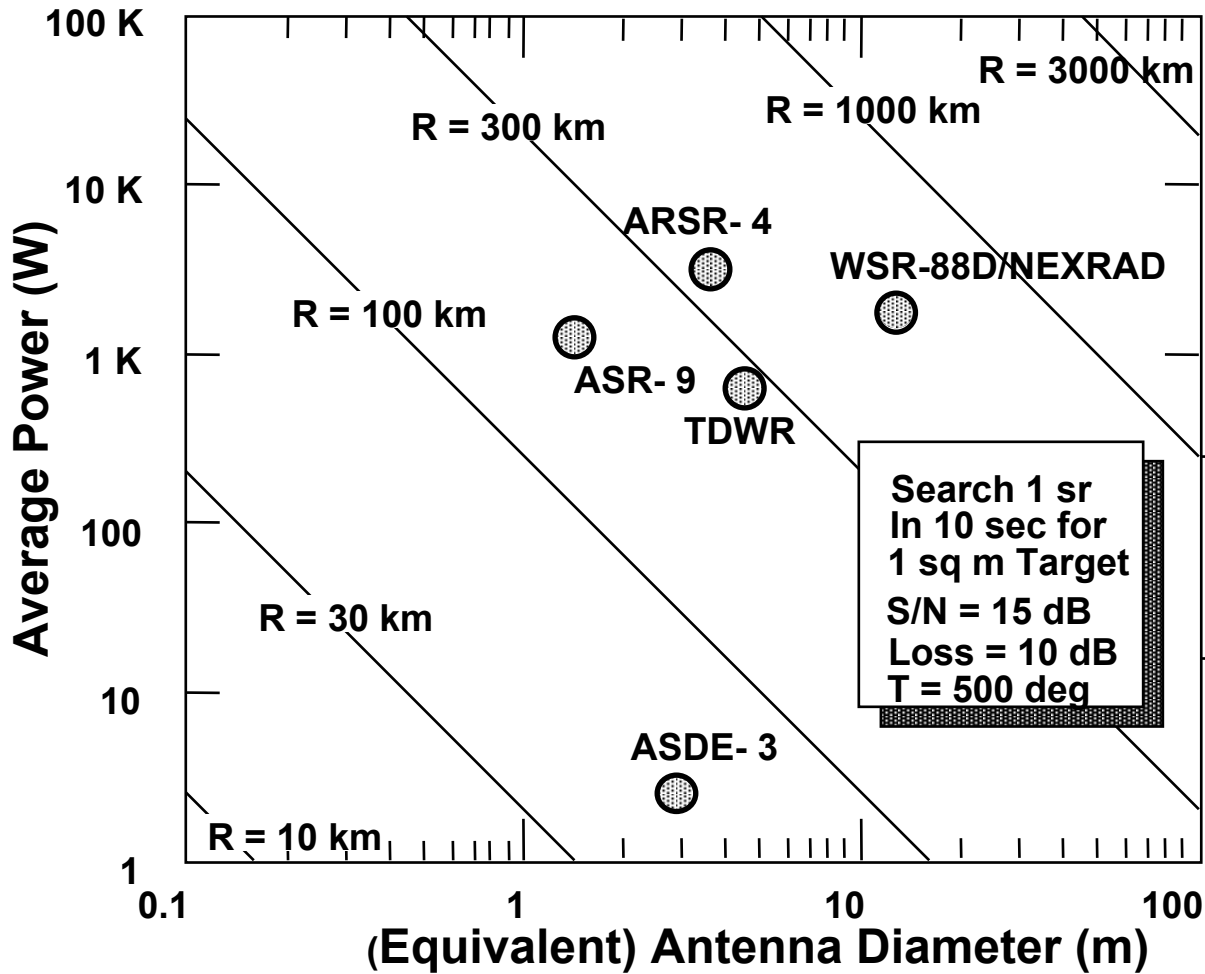


Courtesy Target Corporation

Courtesy of MIT Lincoln Laboratory  
Used with Permission



# Search Radar Performance



Courtesy of MIT Lincoln Laboratory  
Used with Permission

## ARSR-4 Air Route Surveillance Radar



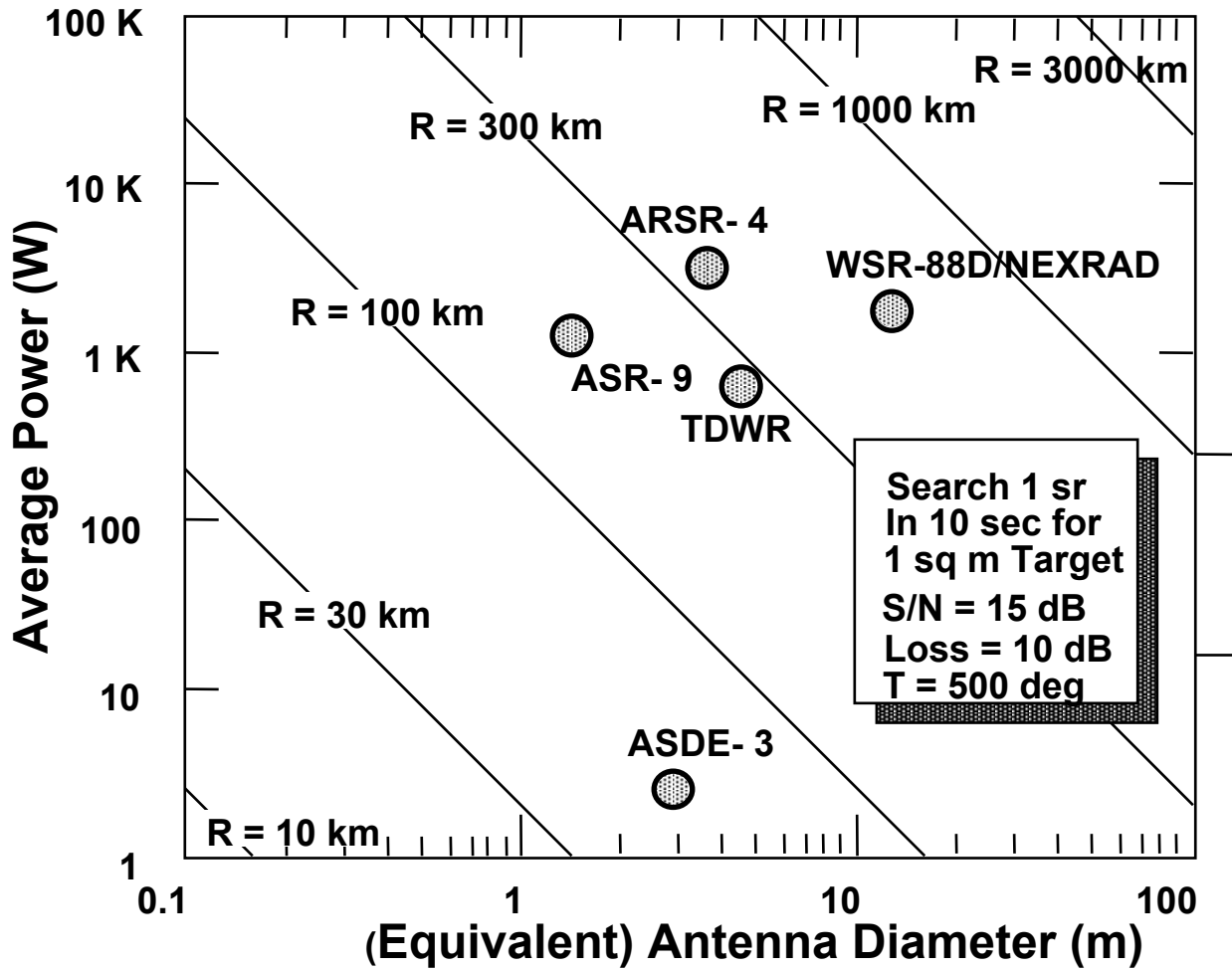
ARSR-4 Antenna  
(without Radome)



Courtesy of Northrop Grumman.  
Used with permission.



# Search Radar Performance



WSR-88D / NEXRAD

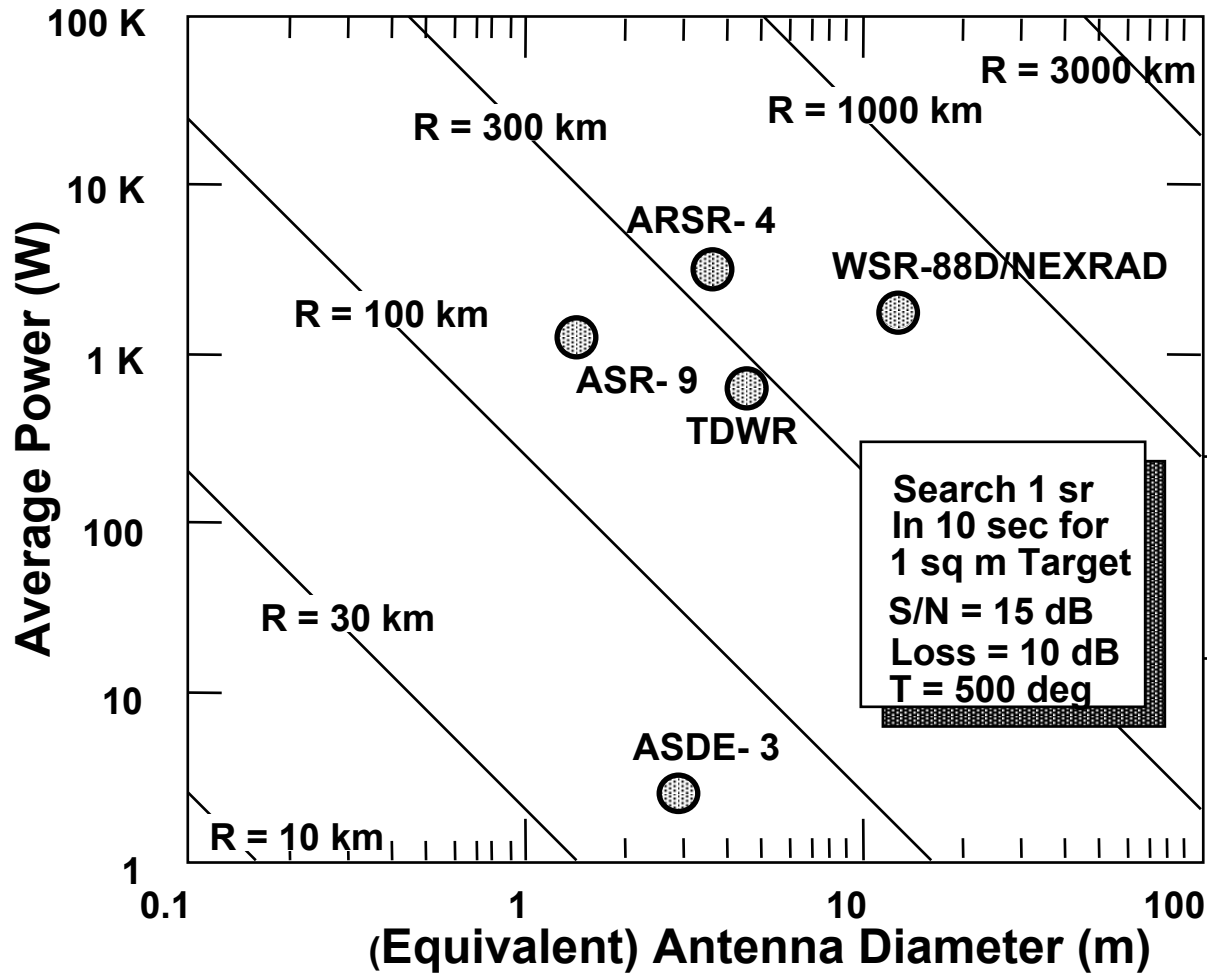


Courtesy of NOAA.

Courtesy of MIT Lincoln Laboratory  
Used with Permission



# Search Radar Performance



**TDWR**  
Terminal Doppler Weather Radar



Courtesy of Raytheon.

Courtesy of MIT Lincoln Laboratory  
Used with Permission



# Outline



- Introduction
- Introduction to Radar Equation
- Surveillance Form of Radar Equation
- ➔ • Radar Equation for Rain Clutter
- Radar Losses
- Example
- Summary



# Radar Equation for Rain Clutter (and other Volume Distributed Targets)



- Standard radar equation  $\rightarrow \frac{S}{N} = \frac{P_t G^2 \lambda^2 \sigma}{(4\pi)^3 R^4 k T_s B_n L}$
- If the target is a diffuse scatterer (e.g. rain), which completely fills the range-azimuth-elevation cell of the radar, then the radar cross section of the target takes the form:

$$\sigma = \eta V \quad \text{and} \quad V = \frac{\pi}{4} (R \theta_B)(R \phi_B) \left( \frac{c \tau}{2} \right) \frac{1}{2 \ln_e 2}$$

- And the radar equation becomes:

$$\frac{S}{N} = \frac{P_t G \lambda^2 c \tau \eta}{1024 (\ln_e 2) R^2 k T_s B_n L}$$

Note, for Gaussian antenna pattern  $G \approx \frac{\pi^2}{\theta_B \phi_B}$

- Note, that volume distributed backscatter is a function of  $1/R^2$  rather than the usual  $1/R^4$





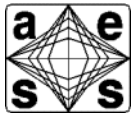
# Outline



- Introduction
- Introduction to Radar Equation
- Surveillance Form of Radar Equation
- Radar Equation for Rain Clutter
- ➔ • Radar Losses
- Examples
- Summary



# System Loss Terms in the Radar Equation



## Transmit Losses

Radome  
Circulator  
Waveguide Feed  
Waveguide  
Antenna Efficiency  
Beam Shape  
Low Pass Filters  
Rotary Joints  
Scanning  
Atmospheric  
Quantization  
Field Degradation

## Receive Losses

Radome  
Circulator  
Waveguide Feed  
Waveguide  
Combiner  
Receiver Protector  
Rotary Joints  
Transmit / Receive Switch  
Antenna Efficiency  
Beam Shape  
Scanning  
Doppler Straddling  
Range Straddling  
Weighting  
Non-Ideal Filter  
CFAR  
Quantization  
Atmospheric  
Field Degradation



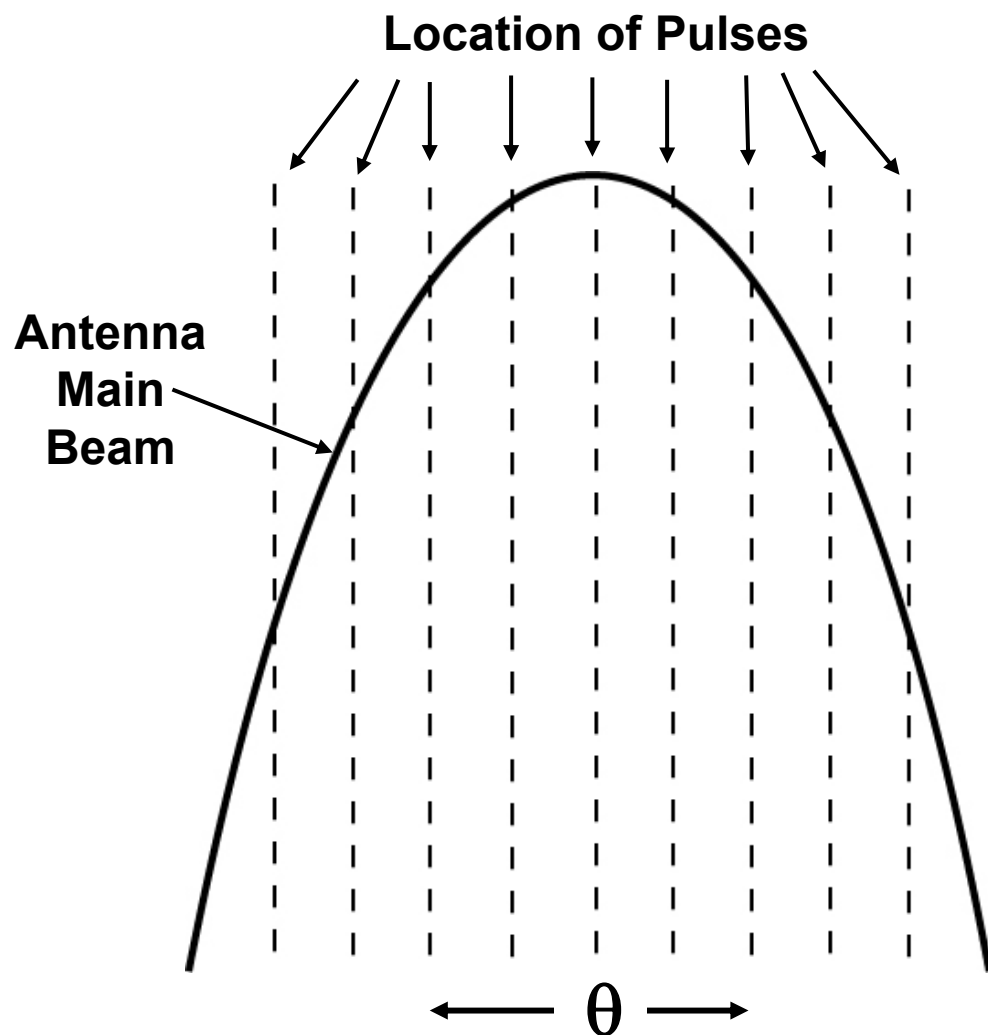
# Major Loss Terms in Radar Equation



- **Beam Shape Loss**
  - Radar return from target with scanning radar is modulated by shape of antenna beam as it scans across target. Can be 2 to 4 dB
- **Scanning Antenna Loss**
  - For phased array antenna, gain of beam less than that on boresite
- **Inputs to System Noise Temperature**
  - Noise received by antenna
    - Local RF noise
    - Galactic noise
  - Receiver noise factor
  - Receive waveguide losses
  - Antenna ohmic losses



# Nature of Beam Shape Loss



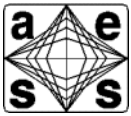
**Radar Equation assumes  $n$  pulses are integrated, all with gain  $G$ .**

**Except for the pulse at the center of the beam, the actual pulses illuminate the target with a gain less than the maximum.**

(Adapted from Skolnik, Reference 1, p 82)



# Major Loss Terms in Radar Equation



- **Waveguide and Microwave Losses**
  - Transmit waveguide losses (including feed, etc)
  - Rotary joints, circulator, duplexer
- **Signal Processing Loss**
  - Range and Doppler Weighting
  - A /D Quantization Losses
  - Adaptive thresholding (CFAR) Loss
  - Range straddling Loss
- **Lens Effect Loss**
  - Refraction in atmosphere causes spreading of beam and thus degradation in S/N
- **Atmospheric Attenuation Loss**
  - Attenuation as radar beam travels through atmosphere (2 way loss)



# Rectangular Waveguide Attenuation

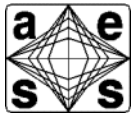


<u>Frequency Band</u>	<u>Frequency Range of Dominant TE<sub>10</sub> Mode (GHz)</u>	<u>Attenuation- Lowest to Highest Frequency (dB/100 ft)</u>
UHF	0.35 - 0.53	0.054 - 0.034
L Band	0.96 - 1.44	0.20 - 0.135
S Band	2.6 - 3.95	1.10 - 0.75
C Band	3.95 - 5.85	2.07 - 1.44
X Band	8.2 - 12.40	6.42 - 4.45
K <sub>u</sub> Band	12.4 - 18.0	9.58 - 8.04
K <sub>a</sub> Band	26.5 - 40.0	21.9 - 15.0

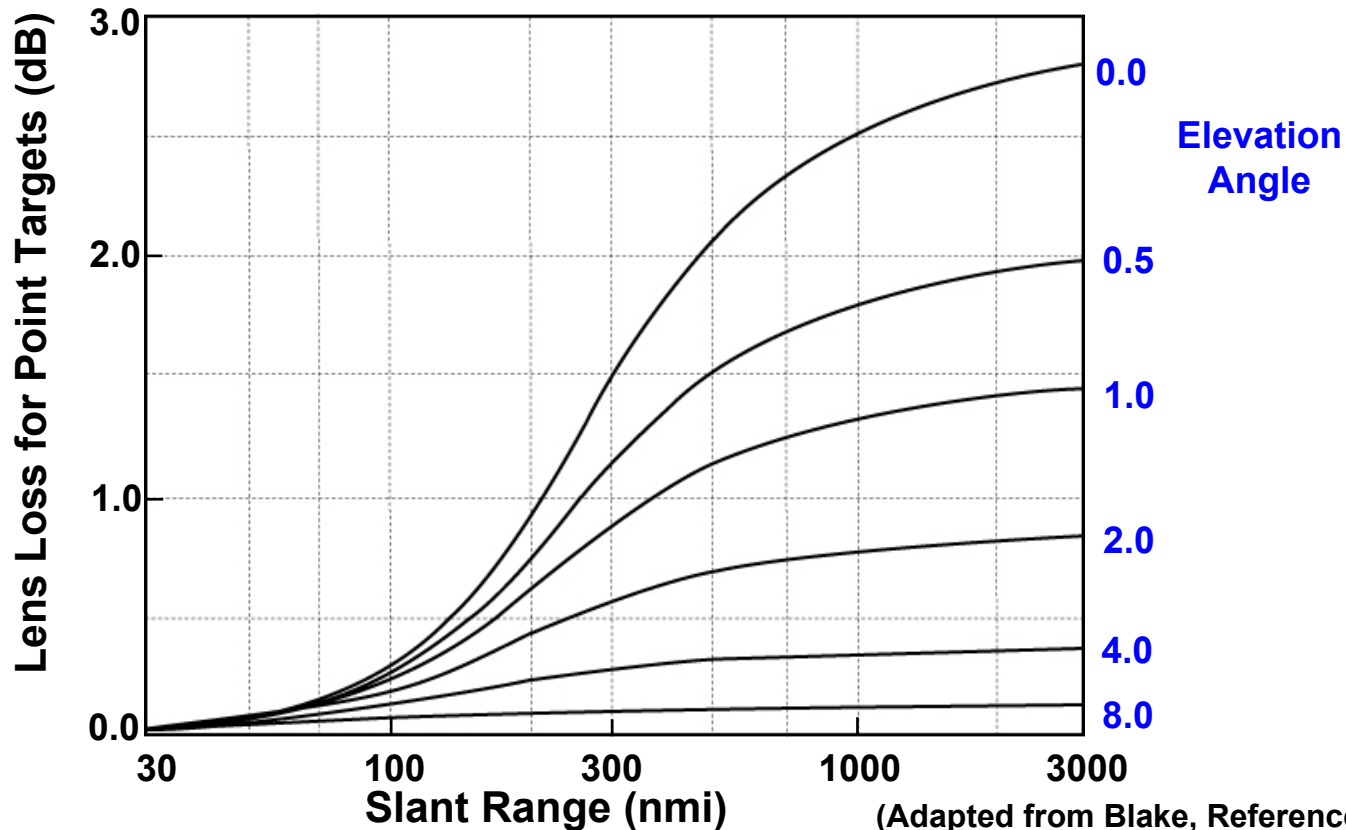
(Adapted from Volakis, Reference 7, pp 51-40 to 51- 41)



# Lens Loss vs. Range



- The gradient of atmospheric refraction at lower elevation angles, causes a spreading of the radar beam, and thus a small diminishment radar power
- This lens loss is frequency independent
- It is significant only for targets that are at long range.

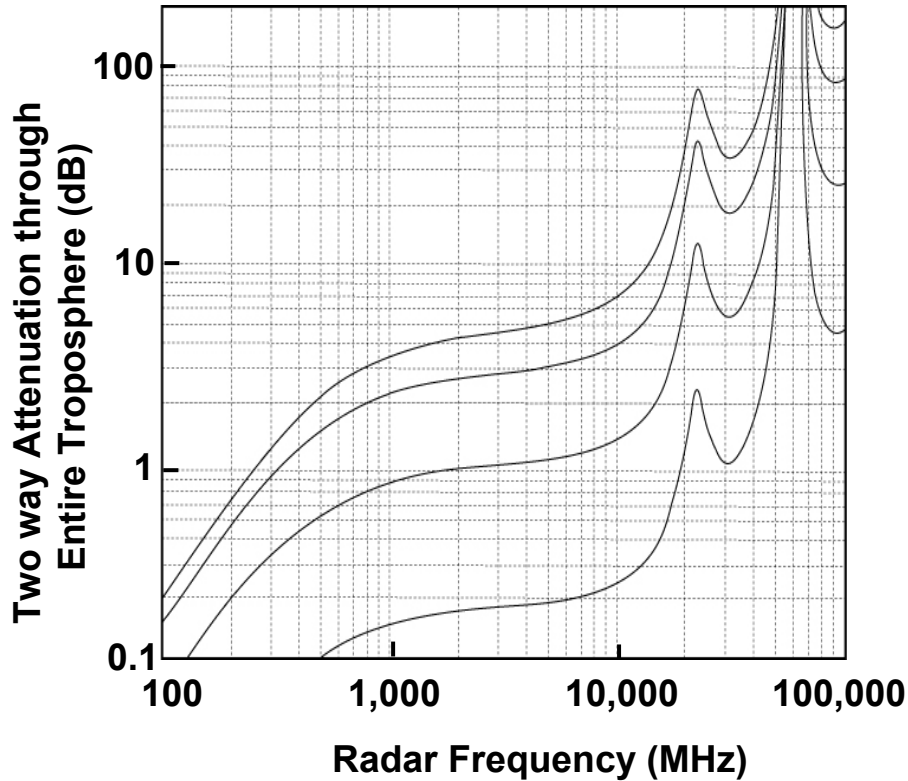




# Loss Due to Atmospheric Attenuation

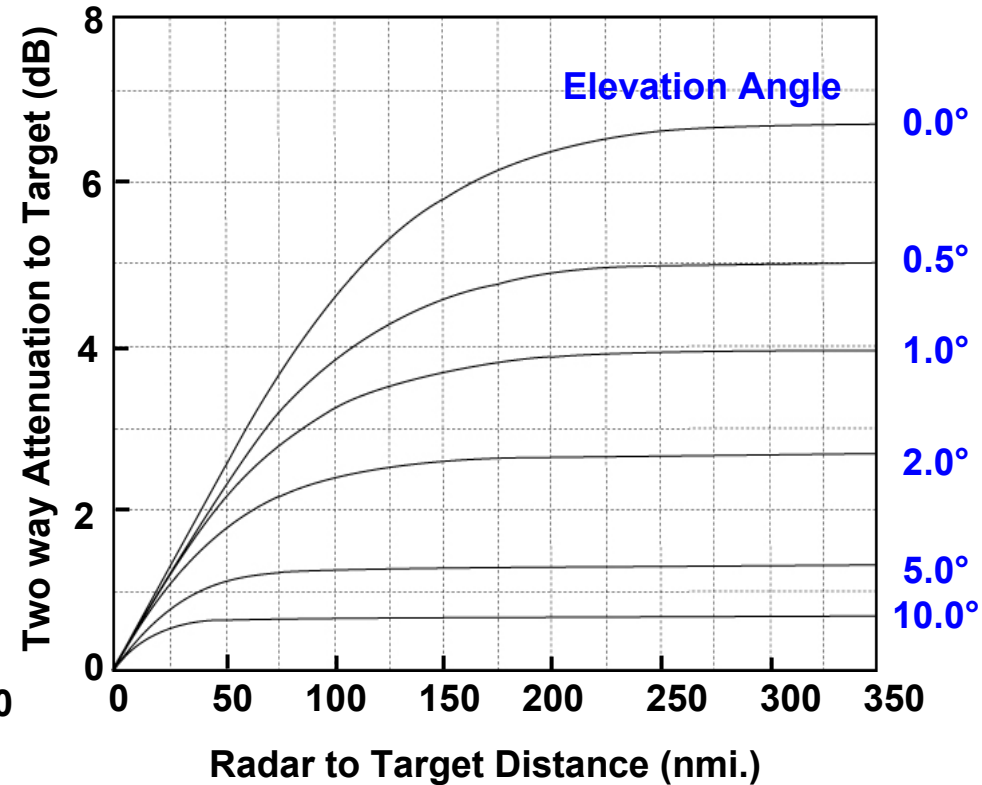


## Attenuation vs. Frequency



0,1,5,30 deg

## Attenuation vs. Range to Target (X-Band 10 GHz)



(Adapted from Blake, see Reference 5, p 192)





# Major Loss Terms in Radar Equation



- **Bandwidth Correction Factor**
  - Receiver not exact matched filter for transmitted pulse
- **Integration Loss**
  - Non coherent integration of pulses not as efficient as coherent integration
- **Fluctuation Loss**
  - Target return fluctuates as aspect angle changes relative to radar
- **Margin (Field Degradation) Loss**
  - Characteristics of radar deteriorates over time (~3 dB not unreasonable to expect over time)
    - Water in transmission lines
    - Weak or poorly tuned transmitter tubes
    - Deterioration in receiver noise figure



# Outline



- Introduction
- Introduction to Radar Equation
- Surveillance Form of Radar Equation
- Radar Equation for Rain Clutter
- Radar Losses
- • Examples
- Summary



# Radar Equation - Examples



- **Airport Surveillance Radar**
  - 0 th order
  - Back of the envelope
  
- **Range Instrumentation Radar**
  - A more detailed calculation



# Example - Airport Surveillance Radar



- **Problem : Show that a radar with the parameters listed below, will get a reasonable S / N on an small aircraft at 60 nmi.**

## Radar Parameters

<b>Range</b>	<b>60 nmi</b>
<b>Aircraft cross section</b>	<b>1 m<sup>2</sup></b>
<b>Peak Power</b>	<b>1.4 Megawatts</b>
<b>Duty Cycle</b>	<b>0.000525</b>
<b>Pulsewidth</b>	<b>.6 microseconds</b>
<b>Bandwidth</b>	<b>1.67 MHz</b>
<b>Frequency</b>	<b>2800 MHz</b>
<b>Antenna Rotation Rate</b>	<b>12.7 RPM</b>
<b>Pulse Repetition Rate</b>	<b>1200 Hz</b>
<b>Antenna Size</b>	<b>4.9 m wide by 2.7 m high</b>
<b>Azimuth Beamwidth</b>	<b>1.35 °</b>
<b>System Noise Temp.</b>	<b>950 ° K</b>

$$\lambda = c / f = .103 \text{ m}$$

$$G = \frac{4\pi A}{\lambda^2} = 15670$$

**= 42 dB, (actually 33 dB  
with beam shaping losses)**

**Number of pulses per  
beamwidth = 21**

**Assume Losses = 8dB**

Courtesy of MIT Lincoln Laboratory  
Used with Permission



# Example - Airport Surveillance Radar



$$\frac{S}{N} = \frac{P_t G^2 \lambda^2 \sigma}{(4\pi)^3 R^4 k T_s B_n L}$$

$$P_t = 1.4 \text{ Megawatts}$$

$$G = 33 \text{ dB} = 2000$$

$$\lambda = .1 \text{ m}$$

$$\sigma = 1 \text{ m}^2$$

$$k = 1.38 \times 10^{-23} \text{ w / Hz } \circ \text{ K}$$

$$R = 111,000 \text{ m}$$

$$T_s = 950 \circ \text{ K}$$

$$B_n = 1.67 \text{ MHz}$$

$$L = 8 \text{ dB} = 6.3$$

$$(4\pi)^3 = 1984$$

$$(1.4 \times 10^6 \text{ w})(2000)(2000)(.1 \text{ m})(.1 \text{ m})(1 \text{ m}^2)$$

$$(1984)(1.11 \times 10^5 \text{ m})^4 (1.38 \times 10^{-23} \text{ w / Hz } \circ \text{ K})(950 \circ \text{ K})(6.3)(1.67 \times 10^6 \text{ Hz})$$

$$\frac{5.6 \times 10^{+6+3+3-1-1}}{415 \times 10^{+3+20-23+2+6}} = \frac{5.6 \times 10^{+10}}{4.15 \times 10^{+2+3+20-23+2+6}} = \frac{5.6 \times 10^{+10}}{4.15 \times 10^{+10}} = 1.35 = 1.3 \text{ dB}$$

$$S / N = 1.3 \text{ dB per pulse (21 pulses integrated)} \Rightarrow S / N \text{ per dwell} = 14.5 \text{ dB} + 13.2 \text{ dB}$$

Courtesy of MIT Lincoln Laboratory  
Used with Permission



# Example - Airport Surveillance Radar



## dB Method

		( + )	( - )
Peak Power	1.4 MW	61.5	
(Gain) <sup>2</sup>	33 db	66	
(Wavelength) <sup>2</sup>	.1 m		20
Cross section	1 m <sup>2</sup>	0	
(4π) <sup>3</sup>	1984		33
(Range) <sup>4</sup>	111 km		201.8
k	1.38 x 10 <sup>-23</sup> w / Hz ° K	228.6	
System Temp	950		29.8
Losses	8 dB		8
Bandwidth	1.67 MHz		62.2
		<u>+ 356.1</u>	<u>- 354.8</u>
			+ 1.3 dB

**S / N = 1.3 dB per pulse (21 pulses integrated) => S / N per dwell = 14.5 dB**  
**( + 13.2 dB)**

Courtesy of MIT Lincoln Laboratory  
 Used with Permission

IEEE New Hampshire Section  
 IEEE AES Society



# Example # 2 – Range Instrumentation Radar

- **Problem :** For a C-band pulsed radar with a 6.5 m dish antenna and 1,000 kW of peak power (0.1% duty cycle), what is the maximum detection range on a target with 0 dBsm cross section, a Pd of .9, and Pfa of  $10^{-6}$  (Assume a Swerling Case 1 target fluctuations and a 1  $\mu$ sec pulse) ?

## Radar Parameters

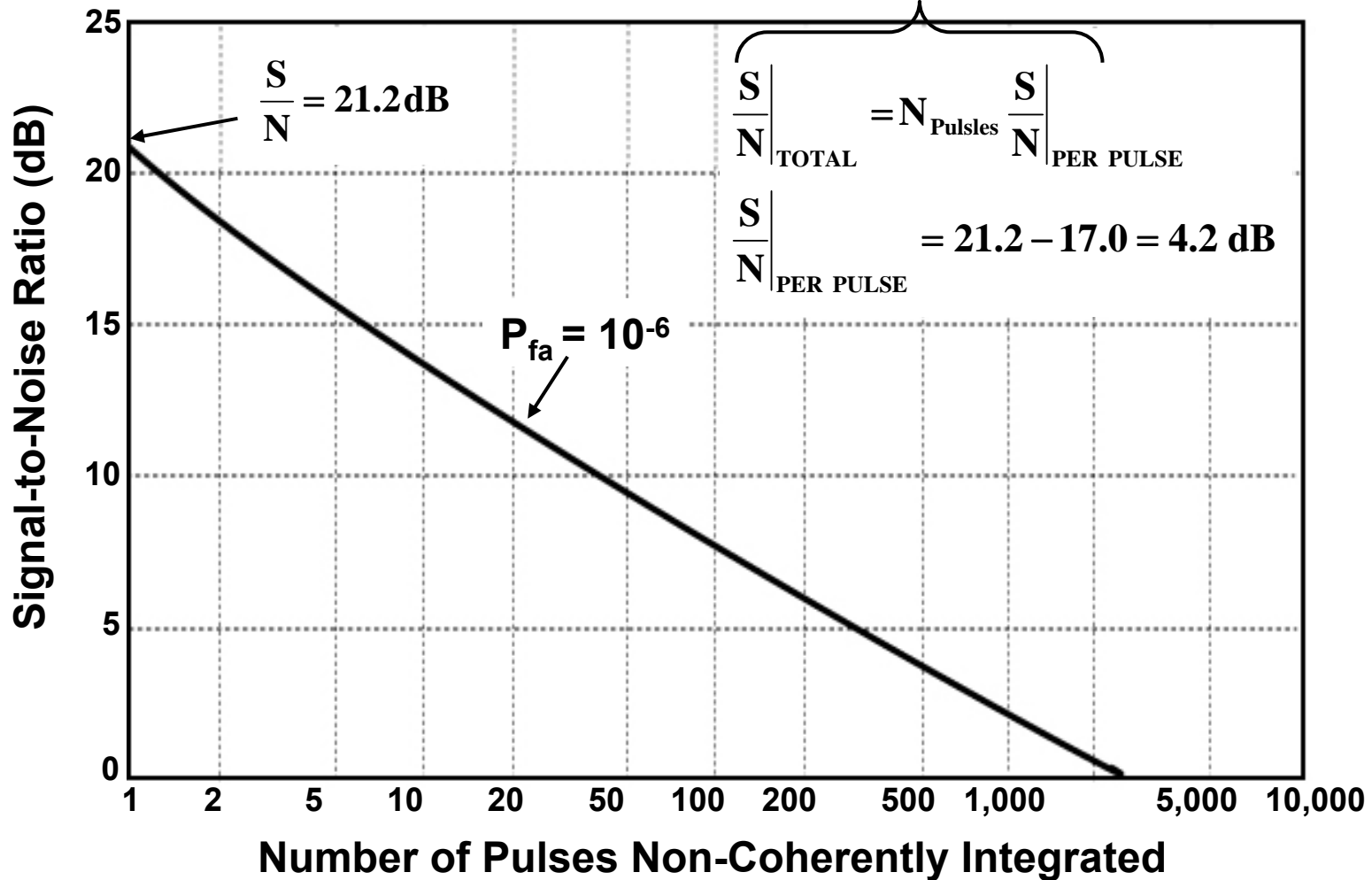
Maximum Detection Range	?? km
Probability of Detection	.9
Probability of False Alarm	$10^{-6}$
Target Cross Section	0 dBsm ( 1 m <sup>2</sup> )
Target Fluctuations	Swerling Case 1
Peak Power	1,000 Kilowatts
Duty Cycle	0.1 %
Pulsewidth	1 microsecond
Frequency	5,500 MHz
Antenna Size	6.5 m dish
Number of Pulses Integrated	50



# Detection Statistics for Swerling Case 1 (Probability of Detection = 0.9)



For Coherent Integration



(Adapted from Blake in Skolnik, see Reference 4, p 192)





# Radar Equation Example #2



• Radar and Target Parameters – Inputs	Natural Units	(dB)
– Peak Power (kilowatts)	1,000	60.0
– Pulse Duration (microseconds)	1.0	- 60.0
– Noise Bandwidth (MHz)	1.0	60.0
– Transmit Antenna Gain (dB)		49.6
– Receive Antenna Gain (dB)		49.6
– Frequency (GHz)	5.5	
– Wavelength (meters)	5.45	- 25.3
– Single Pulse Signal to Noise Ratio		4.2
– Target Radar Cross Section (meters) <sup>2</sup>	1.0	0.0
– k - Boltzmann's Constant $1.38 \times 10^{-23}$ (w / Hz °K )		- 228.6
– $(4\pi)^3$		33.0
– System Noise Temperature ( °K )	598.2	27.8
– Total System Losses		9.0
– Range (kilometers)	519	

## Antenna

Efficiency	65 %
Diameter (meters)	6
Gain (dB)	49.6



# Radar Equation # 2

# System Losses



<b>System Losses</b>	<b>(dB)</b>	<b>Transmit Losses</b>	<b>(dB)</b>
Bandwidth Correction Factor (dB)	0.70	Circulator (dB)	0.40
Transmit Loss (dB)	1.30	Switches (dB)	0.40
Scanning Antenna Pattern Loss (dB)	0.00	Transmission Line	<u>0.50</u>
Signal Processing Losses (dB)	1.90		1.30
Atmospheric Attenuation Loss (dB)	1.80		
Lens Effect Loss (dB)	0.25		
Integration Loss (dB)	0.00		
Target Fluctuation Loss (dB)	0.00	<b>Signal Processing Losses</b>	<b>(dB)</b>
Margin / Field Degradation Loss (dB)	<u>3.00</u>	Threshold Loss (dB)	0.50
<b>Total Loss Budget (dB)</b>	<b>8.95</b>	A/D Quantization Loss (dB)	0.10
		Range Straddling Loss	0.20
		Weighting Loss	<u>1.10</u>
			1.90
<b>Loss – Input to System Noise Temperature</b>			
Receiver Noise Factor (dB)	4.00		
Antenna Ohmic Loss (dB)	0.20		
Receive Transmission Line loss (dB)	0.40		
Sky Temperature (°K)	50.00		
C-Band at 3°			

$$T_s = T_a + T_r + L_r T_e = 598.2^\circ \text{K}$$

$$T_a = (0.88 T_{\text{sky}} - 254) / (L_a + 290)$$

$$T_r = T_{\text{tr}} (L_r - 1) \quad \text{and} \quad T_e = T_0 (F_n - 1)$$



# Outline



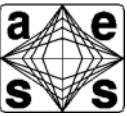
- Introduction
- Introduction to Radar Equation
- Surveillance Form of Radar Equation
- Radar Equation for Rain Clutter
- Radar Losses
- Examples
- • Summary



# Cautions in Using the Radar Equation (1)



- **The radar equation is simple enough, that just about anyone can learn to use and understand**
- **Unfortunately, the radar equation is complicated enough that anyone can mess it up, particularly if you are not careful**
  - **See next viewgraph for relevant advice**



## The Sanity Check

- Take a Candidate Radar Equation

- Check it Dimensionally

- $R$  and  $\lambda$  are distance
- $\sigma$  is distance squared
- $P_t$  is energy / time
- $S/N$ ,  $G$ , and  $L$  are dimensionless
- $kT_s$  is energy
- $B_n$  is (time)<sup>-1</sup>

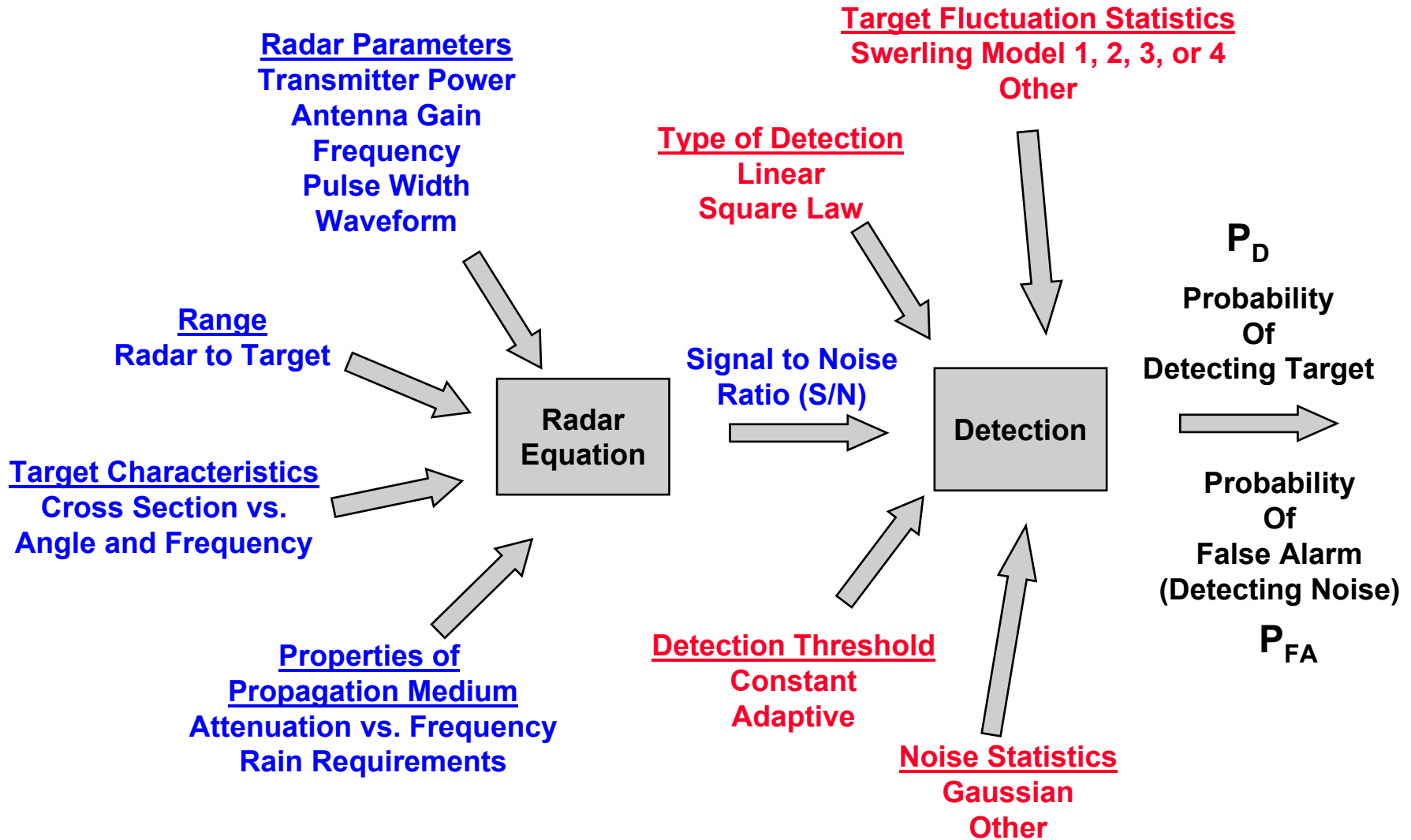
- Check if Dependencies Make Sense

- Increasing **Range** and **S/N** make requirements tougher
- Increasing **Power** and **Antenna Gain** make radar more capable
- Decreasing **Wavelength** and **Radar Cross Section** make the radar less capable

$$\frac{S}{N} = \frac{P_t G^2 \lambda^2 \sigma}{(4\pi)^3 R^4 k T_s B_n L}$$



# Radar Equation and the Detection Process





# Summary



- **The radar equation relates:**
  - Radar performance parameters - Detection range, S/N, etc.  
and
  - Radar design parameters - Transmitter power, antenna size, etc.
- **There are different forms of the radar equations for different radar functions**
  - Search, Track
- **Scaling of the radar equation allows the radar designer to understand how the radar parameters may change to accommodate changing requirements**
- **Be careful, if the radar equation leads to unexpected results**
  - Do a sanity check !  
Look for hidden variables or constraints  
Compare parameters with those of a real radar



# References



1. Skolnik, M., *Introduction to Radar Systems*, McGraw-Hill, New York, 3<sup>rd</sup> Ed., 2001
2. Barton, D. K., *Modern Radar System Analysis*, Norwood, Mass., Artech House, 1988
3. Skolnik, M., Editor in Chief, *Radar Handbook*, New York, McGraw-Hill, 3<sup>rd</sup> Ed., 2008
4. Skolnik, M., Editor in Chief, *Radar Handbook*, New York, McGraw-Hill, 2<sup>nd</sup> Ed., 1990
5. Blake, L. M., *Radar Range Performance Analysis*, Silver Spring, Maryland, Munro, 1991
6. Nathanson, F. E., *Radar Design Principles*, New York, McGraw-Hill, 1<sup>st</sup> Ed., 1991
7. Volakis, J. L., *Antenna Engineering Handbook*, McGraw-Hill, New York, 4<sup>th</sup> Ed., 2007





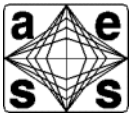
# Contributors



- **Dr Stephen D. Weiner**
- **Dr. Claude F. Noiseux**



# Homework Problems



- **From Reference 1, Skolnik, M., Introduction to Radar Systems, 3<sup>rd</sup> Edition, 2001**
  - **Problem 1-5**
  - **Problem 1-6**
  - **Problem 2-22**
  - **Problem 2-24**
  - **Problem 2-25**